## Computational

Chemistry
Van 't Hoff Institute for Molecular Sciences

MULTISCALE SIMULATIONS OF BIOMOLECULAR SYSTEMS

## Coarse-graining

## Why? What? How?



## Why? What?

Time / [s]

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hat?





## Robert J. Oppenheimer

1904-1967
"Father of the atomic bomb" Born-Oppenheimer approximation (1927) electronic motion and nuclear motion in molecules can be separated


Richard Feynman
1918-1988
1965 - Nobel price
development of quantum electrodynamics 1959 - designing miniaturized machines


## Paul Dirac

1902-1984
1933 - Nobel price discovery of new productive forms of atomic theory


## Erwin Schrödinger

1887-1961
1933 - Nobel price discovery of new productive forms of atomic theory $\mathrm{i} \hbar \frac{\partial}{\partial t}|\psi(t)\rangle=\hat{H}|\psi(t)\rangle$


## Niels Bohr

1885-1962
1922 - Nobel price investigation of the structure of atoms and the radiation emanating from them
Developed the model for the atom


Werner Heisenberg 1901-1976 1932 - Nobel price creation of quantum mechanics

$$
\Delta x \Delta p \geq \frac{h}{4 \pi}
$$

Before CG


Martin Karplus


Michael Levitt


Arieh Warshel

Multiscale models
for complex
chemical systems


1940-1950s
Analytical Engine
ENIAC

1966


Charles Babbage
(1791-1871)
Analytical Machine

2020

2013


Density functional theory \& Computational methods in quantum chemistry

## AlphaFold \& ML

## 1930s

$\mathrm{H}, \mathrm{He}, \mathrm{H}_{2}$


Paul Dirac


Molecular orbital theory \& its use in the calculation of electronic structure of molecules
the era of computing chemists, when hundreds if not thousands of chemists will go to the computing machine instead of the laboratory for increasingly many facets of chemical information, is already at hand.


Niels Bohr
Erwin Schrodinger
Werner Heisenberg
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## The basics - structural resolution



Ethene in electronic structure level representation (orbitals)


Ethene in all-atom molecular mechanics representation (spheres)

Ethene in coarse-grained representation

## Molecular Mechanics Representation



- Atom $\rightarrow$ sphere
- Biomolecular force field: shapes the collection of spheres into things that look like molecules through so-called bonded interactions
- Force field: atom-atom interactions of distal parts through nonbonded interactions.
- Electronic structure is in general coarse-grained out and expected to be captured by the force field.

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The basics on one slide (classical simulations)

$$
\begin{aligned}
\mathrm{V} & =\sum_{\text {All Bonds }}^{1} \frac{1}{2} \mathrm{~K}_{b}\left(b-b_{0}\right)^{2}+\sum_{\text {Hate } 1635}^{\frac{1}{2}} \mathrm{~K}_{\theta}\left(\theta-\theta_{0}\right. \\
& +\sum_{\text {Angles }} \mathrm{K}_{\phi}[1-\cos (n \phi+\delta)]
\end{aligned}
$$

$$
\begin{aligned}
& F=m \frac{d^{2} r}{d t^{2}}=m a \\
& F=-\frac{d V(r)}{d r}
\end{aligned}
$$

All Torsion Angles


$$
+\sum \varepsilon\left[\left(r_{0} / r^{12}-2\left(r_{0} / r\right)^{6}\right]\right.
$$

All Nonbonded pairs
Van der Waals 1837
$+\sum_{\text {All partial charges }} 332 q_{j} / r$
Coulomb 1736

over many terms


## How does it work?

- The force field is an analytical function of the spatial coordinates of the atomic nuclei
- Several different force fields are commonly available (CHARMM, AMBER, OPLS)

$$
\begin{aligned}
F & =m \frac{d^{2} r}{d t^{2}}=m a \\
F & =-\frac{d V(r)}{d r} \quad \begin{array}{l}
\text { Given the potential, one can numerically } \\
\text { integrate the trajectory of the whole system } \\
\text { as a function of time. }
\end{array} \\
\mathrm{V} & =\mathrm{V}_{\text {bonds }}+\mathrm{V}_{\text {angles }}+\mathrm{V}_{\text {dihedral }}+\mathrm{V}_{\text {nonce } \mathrm{F} \text { is given by the gradient }}
\end{aligned}
$$

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$$
\mathrm{V}=\mathrm{V}_{\mathrm{bonds}}+\mathrm{V}_{\mathrm{angles}}+\mathrm{V}_{\text {dihedrals }}+\mathrm{V}_{\text {nonbonded }}
$$

$$
\mathrm{V}=\mathrm{V}_{\text {bonds }}+\mathrm{V}_{\text {angles }}+\mathrm{V}_{\text {dihedrals }}+\mathrm{V}_{\text {nonbonded }}
$$

the energy needed to stretch a covalent bond between two atoms by Hooke's law for the potential energy stored in a spring

$$
V_{b o n d s}\left(r_{i j}\right)=k_{i j}^{B}\left(r_{i j}-r_{i j}^{0}\right)^{2}
$$

$k_{i j}^{B}$ - constant (bond stiffness)
$r_{i j}^{0}$ - equilibrium distance

the energy needed to bend the angle formed by two covalent bonds

$$
V_{\text {angles }}\left(\theta_{i j k}\right)=k_{i j k}^{\theta}\left(\theta-\theta_{i j k}^{0}\right)^{2}
$$

$$
k_{i j}^{\theta} \text { - constant (angle rigidity) }
$$ $k_{i j}^{\theta}$ - constant (angle rigidity)

$$
\theta_{i j k}^{0} \text { - equilibrium angle width }
$$


the energy needed to bend the dihedral angle formed by three covalent bonds

$$
\begin{aligned}
& V_{\text {dihedrals }}\left(\varphi_{i j k l}\right) \\
& =k_{i j k l}^{\varphi}\left[1+\cos \left(n \varphi_{i j k l}-\delta\right)\right]
\end{aligned}
$$



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$$
\mathrm{V}=\mathrm{V}_{\text {bonds }}+\mathrm{V}_{\text {angles }}+\mathrm{V}_{\text {dihedrals }}+\mathrm{V}_{\text {nonbonded }}
$$

for non-covalently bound atoms
$\mathrm{V}_{\mathrm{vdW}}+\mathrm{V}_{\text {electrostatic }}$

$$
\mathrm{V}_{\mathrm{vdW}}+\mathrm{V}_{\text {electrostatic }}
$$

$V_{v d W}=4 \epsilon\left[\left(\frac{\sigma}{r_{i j}}\right)^{12}-2\left(\frac{\sigma}{r_{i j}}\right)^{6}\right]$

$\varepsilon_{d}$ - dielectric constant of the surrounding medium

$$
V_{\text {electrostatic }}=\frac{q_{i} q_{j}}{\varepsilon_{d} r_{i j}}
$$ $q_{i}, q_{j}$ - charges


$\mathrm{V}=\mathrm{V}_{\text {bonds }}+\mathrm{V}_{\text {angles }}+\mathrm{V}_{\text {dihedrals }}+\mathrm{V}_{\text {nonbonded }}$

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## The dream!



## Intermezzo - Why?

CONVEX SUPERCOMPUTER - DATA PROCESSOR (1989, U.S.A)
The Convex Company was founded in 1982, with a view to creating supercomputers for the technical and scientific field. Similar to the Cray computers, the Convex is based on vectors or a system that is parallel with the vector-type registers, thus reducing the bandwidth of the available memory for each processor to a single operation per cycle. Convex invested
massive amounts of money into automatic vectorization techniques.
The Convex C 1 is a vector-type computer with a single processor,
which came out in 1985. The Convex supercomputer runs with the UNIX operating system, the OS version, called Convex OS, and it is equipped with
type $C$ automatic parallelizing compilers and Fortran.

Technical specifications:


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## How does it work?

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## Water models

- Rigid
- Fixed atom positions
- Only non-bonded interactions
- Flexible
- Atoms on "springs"

- Include bond stretching and angle bending
- Reproduce vibration spectra
- Polarizable
- Include specific polarization terms

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## Rigid water models



3-site


$$
V=\sum_{\text {pairs }} \underbrace{\frac{A_{L J}}{r_{O-O}^{12}}-\frac{B_{L J}}{r_{O-O}^{6}}}_{\text {LJ for O-O }}+\underbrace{k \frac{q_{i} q_{j}}{r_{i j}}}_{\text {Coulomb }})
$$


$r_{O-O}$ oxygen-oxygen distances $A_{L J}, B_{L J}$ Lennard-Jones parameters $r_{i j}$ distance between charged sites $k$ constant in Coulomb's law

## Radial distribution function $\mathrm{g}(\mathrm{r}$ )



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Small differences in geometry, charges
but huge differences in water structure and
Small differences in geometry, charges
but huge differences in water structure and dynamics

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Example
Average number of water molecules in the first two solvation shells

|  | TIP3P | TIP4P | TIP5P | SPC/E |
| :--- | :--- | :--- | :--- | :--- |
| first shell, $<3.4 \AA$ | $93 \pm 8$ | $93 \pm 6$ | $100 \pm 8$ | $94 \pm 7$ |
| second shell, $<5.0 \AA$ | $185 \pm 14$ | $182 \pm 12$ | $196 \pm 15$ | $186 \pm 13$ |
| long-residency water molecules | $0.0 \pm 0.0$ | $2.0 \pm 1.3$ | $12.8 \pm 4.5$ | $3.7 \pm 2.7$ |



Water density maps

## BUT ...



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$2+2+2+2$ $\square$


## Implicit solvent models

- Represent solvent and counterions as a continuum $\rightarrow$ solvent degrees of freedom are taken into account implicitly
- Solvent $=$ high dielectric medium \& protein $=$ low dielectric region \& spatial charge distribution
- No need of water equilibration
- Much faster than explicit solvent $\rightarrow$ lower computational cost
- Examples
- Poisson-Boltzmann model
- Generalized Born model
- ABSINTH model (explicit ions)


## Implicit solvent models

- seek to approximate is the solute potential of mean force, which determines the statistical weight of solute conformations, and which is obtained by averaging over the solvent degrees of freedom.
- the total free energy = the reversible work performed in two successive steps
- the particle is inserted in the solvent with zero atomic partial charges
- the atomic partial charges of the particle are switched from zero to their full values
the total solvation free energy corresponds to a sum of non-polar and
- the atomic partial charges of the particle are switched from zero to their
- the total solvation free energy corresponds to a sum of non-polar and electrostatic contributions

$$
\Delta G_{\text {solv }}=\Delta G_{\text {polar }}+\Delta G_{\text {nonpolar }}
$$

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## Implicit solvent models

$$
\Delta \mathrm{G}_{\text {solv }}=\underset{\substack{\text { polar } \\ \\ \\ \\ \\ \text { Electrostatics } \\ \text { Poisson-Boltzmann }}}{\Delta \mathrm{G}_{\text {nonpolar }}} \underset{\downarrow}{\Delta \mathrm{G}_{\text {cav }}+\Delta \mathrm{G}_{\mathrm{vdW}}}
$$

$\Delta \mathrm{G}_{\text {cav }}$ - cavity creation within the solvent
$\Delta \mathrm{G}_{\mathrm{vdW}}$ - embedding of the particle into the cavity

Solute shape cavity of vacuum is introduced into the solvent

Solvent molecules reorient and polarize in response to the solute charge density


Solute charge density is placed in the solute cavity

Solute polarizes in response
to solvent polarization


In explicit solvent 1.6 M atoms

## An example <br> NIVERSITEIT VAN AMSTERDAM <br> 23 <br> $\qquad$



231


In implicit solvent
Glycans
$\Delta t=2 \mathrm{fs}$

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\Delta \mathrm{t}=5 \mathrm{fs}
$$



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## Membrane-interaction mechanisms

## PrPC

POM1

## POM6


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## Cows, Langevin \& Brown - Can we do more?



Solvent molecules
<collisions solvent > fluctuations around $\xi$
(thermal noise of solvent molecules)

$\rightarrow \quad$ friction, $\xi$ stochastic Markovian process

## Langevin \& Brown



$$
\begin{aligned}
& \boldsymbol{v}=\frac{\mathrm{d} \boldsymbol{r}}{\mathrm{dt}} \\
& m \frac{\mathrm{~d} \boldsymbol{v}}{\mathrm{dt}}=-\boldsymbol{F}_{D}+\boldsymbol{F}_{B}
\end{aligned}
$$

From hydrodynamics $\quad \boldsymbol{F}_{D}=6 \pi \eta \boldsymbol{v} r$

$$
m \frac{\mathrm{~d} \boldsymbol{v}}{\mathrm{dt}}=-6 \pi \eta \boldsymbol{v} r+\boldsymbol{F}_{B}
$$

Friction force Random force

$$
\xi=6 \pi \eta r / m
$$

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$\underset{\mathrm{d} \mathbf{v}}{\text { Langevin dynamics }}$

$$
\begin{gather*}
\left\langle\mathbf{F}_{B}(t)\right\rangle=0 \quad \text { Noise produces no net force } \\
\left\langle\mathbf{F}_{B}(t) \cdot \mathbf{F}_{B}\left(t^{\prime}\right)\right\rangle=2 k_{B} T \xi \delta\left(t-t^{\prime}\right) \\
\text { Fluctuation-dissipation theorem } \\
\text { Balance between "dead" and "alive" }
\end{gather*}
$$

# $$
\begin{aligned} m \frac{\mathrm{~d} \mathbf{v}}{\mathrm{dt}}= & -6 \pi \eta \mathbf{v} r+\mathbf{F}_{B} \\ \rightarrow & \mathbf{v}(\mathrm{t})=\mathbf{v}_{0} \mathrm{e}^{-\xi t / m}+\int_{0}^{t} \mathrm{~d} \tau \mathrm{e}^{-\xi(t-\tau) / m} \frac{1}{m} \mathbf{F}_{B}(\tau) \\ & \mathbf{v}^{2}(t \rightarrow \infty) \approx 0 \text { false } \end{aligned}
$$ <br> $$
x-2-1
$$ 

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## $\delta$-Dirac function

No correlation between $t$ and $\mathrm{t}^{\prime}$ due to time scale separation (short lived collisions)
20
(shortived collisions)
an
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## Langevin dynamics

$$
m \ddot{\mathbf{r}}=-\xi \dot{\mathbf{r}}+\mathbf{F}(\mathbf{r})+\sigma \mathbf{R} \quad \sigma=2 k_{B} T \xi
$$

Reduced degrees of freedom
Focus on the important contributions

Keeps the contributions to the dynamics of the system

Long chain molecules
Barrier crossing motions






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- No inertia (high friction)





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#### Abstract


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$$
\left.\begin{array}{ll}
m \ddot{\mathbf{r}}=-\xi \dot{\mathbf{r}}+\mathbf{F}(\mathbf{r})+\sigma \mathbf{R} \quad \sigma=2 k_{B} T \\
<m \ddot{\mathbf{r}}>_{\Delta t} \cong 0
\end{array}\right\} \Delta \mathbf{r}=\frac{\mathbf{F}}{\xi}+\sqrt{\frac{2 k_{B} T \Delta t}{\xi}} \mathbf{R}
$$

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## In practice



$$
\begin{aligned}
& \mathbf{r}(t+\delta t)-\mathbf{r}(t)=\quad \boldsymbol{\mu}^{\boldsymbol{t}} \quad \mathbf{F} \boldsymbol{\delta} \boldsymbol{t}+ \\
& \sqrt{\boldsymbol{\mu}^{t}} \boldsymbol{\Theta}^{\mathrm{t}}(t) \sqrt{2 k_{B} T \delta t}
\end{aligned}
$$

$$
\begin{aligned}
& \left.<(\mathbf{r}(t)-\mathbf{r}(0))^{2}\right\rangle=6 D_{t} \delta t \\
& \Theta_{\alpha}^{i}\left\{\begin{array}{c}
\left\langle\Theta_{\alpha}^{i}(t)\right\rangle=0 \\
\left\langle\Theta_{\alpha}^{i}(t) \Theta_{\beta}^{i}\left(t^{\prime}\right)\right\rangle=\delta_{\alpha \beta} \delta_{i j} \delta_{t t^{\prime}}
\end{array}\right.
\end{aligned}
$$

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## In practice

$$
\mathbf{q}(t+\delta t)-\mathbf{q}(t)=\mathbf{A} .
$$

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$\mathbf{q}(t+\delta t)-\mathbf{q}(t)=\mathbf{B} \cdot \boldsymbol{\mu}^{\mathrm{r}} \cdot \mathbf{A}^{\mathrm{T}} \mathbf{T} \boldsymbol{\delta} \boldsymbol{t}+\mathbf{B} \sqrt{\boldsymbol{\mu}^{\mathrm{r}}} \boldsymbol{\Theta}^{\mathrm{r}}(t) \sqrt{2 k_{B} T \delta t}+\lambda \mathbf{q}$

$$
\begin{aligned}
& q(t+\boldsymbol{\delta} t)=1 \\
& \boldsymbol{\lambda}^{2}+2 \boldsymbol{\lambda} \mathbf{q}(t) \cdot \tilde{\mathbf{q}}(t+d t)+\tilde{\mathbf{q}}^{2}(t+\boldsymbol{\delta} t)=1
\end{aligned}
$$

## Intermezzo - the ideal gas and beyond

Janus particles


Striped nanospheres


Striped nanorods



DNA patchy particles


DNA patches

## An example - proteins as patchy particles ()



www.endocytosis.org

## The model clathrin


28 Mini coat

32 Sweet potato

36 D6 barrel


36 Tennis ball


37 Big apple


20 Dice

24 Brussel

26 Pumpkin

28 Mini coat

32 Sweet
potato (L)

32 Sweet potato (R)


38 Big
 38 Big
c


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The model


## $5025 \mathrm{AA} \rightarrow 645 \mathrm{kDa}$

## a PIECE!!!!

Atomistically impossible
$\rightarrow$ coarse graining


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Coarse-grained model: one protein $=1$ rigid particle




Coarse-grained model: one protein = rigid particle
Coarse-grained model: one protein = rigid particle


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domain
s.
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## What do we need?

- Friction
- Interaction potential
- A good cluster

$$
\begin{aligned}
\mathbf{r}(t+\delta t)-\mathbf{r}(t)= & \mathbf{A} \cdot \boldsymbol{\mu}^{\boldsymbol{t}} \cdot \mathbf{A}^{\mathrm{T}} \mathbf{F} \boldsymbol{\delta} \boldsymbol{t}+ \\
& \mathbf{A} \cdot \sqrt{\boldsymbol{\mu}^{t}} \boldsymbol{\Theta}^{\mathrm{t}}(t) \sqrt{2 k_{B} T \delta t}
\end{aligned}
$$

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## Diffusion

## ，

|  | HYDRO＋＋ |
| :--- | :--- |
|  | Input |
| M．W． | 645 kDa |
| $\eta$ | 0.01 Poise |
| $\chi$ | $101^{\circ}$ |
| $T$ | $20^{\circ} \mathrm{C}$ |
|  | Output |
| $D^{\mathrm{t}}$ | $1.22 \cdot 10^{-7} \mathrm{~cm}^{2} / \mathrm{s}^{* *}$ |
| $D^{\mathrm{r}}$ |  |


|  | HYDRO＋＋ |
| :--- | :--- |
|  | Input |
| M．W． | 645 kDa |
| $\eta$ | 0.01 Poise |
| $\chi$ | $101^{\circ}$ |
| $T$ | $20^{\circ} \mathrm{C}$ |
|  | Output |
| $D^{\mathrm{t}}$ | $1.22 \cdot 10^{-7} \mathrm{~cm}^{2} / \mathrm{s}^{* *}$ |
| $D^{\mathrm{r}}$ |  |

Input

## 

$$
\begin{equation*}
\text { Diffusion matrices } \quad D=\frac{k_{B} T}{\xi} \tag{保}
\end{equation*}
$$



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[^1]
## The potential

$$
\Phi=-\varepsilon \cdot f(r)
$$

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## The potential

- interaction between leg segments

$$
\Phi=-\varepsilon \cdot f(r)
$$

- asymmetric binding

- Rotational asymmetry



| N particles | 200 |
| :--- | :--- |
| c | $100 \mu \mathrm{~g} / \mathrm{ml}$ |
| T | $\mathrm{Temp}=20^{\circ} \mathrm{C}$ |
| $\delta \mathrm{t}$ | 10 ns |
| timescale | 4 s |
| box length | $1 \mu \mathrm{~m}$ |




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## How to CG? What is my research question?

(a)

(c)



## Growth phase:

- Primary nucleation
- Fibril elongation
- Fragmentation
- Secondary nucleatio
- Oligomers
- Free monomers
- Misfolded aggregates
- Fibril extension


## Saturation phase:

- Mature fibril



## Aggregate formation



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## Aggregates $=$ Oligomers



Released toxic oligomers

Backward oligomers


What are the aggregation mechanisms?


[^2]
## Off-pathway <br> Off-pathway oligomers

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\section*{What is my research question? Aggregation}
(a)

(c)

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\section*{Aggregates = oligomers}



\[
\Phi=\sum_{i, j} \Phi_{e x . v}\left(r_{i j}\right)+\sum_{i, j} \Phi_{a t t r}\left(r_{i j}\right)+\sum_{i, j} \Phi_{a t t r}\left(d_{i j}, \widehat{\boldsymbol{u}}_{i,} \widehat{\boldsymbol{u}}_{j}\right)
\]


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\section*{Single-strand protofilaments}


和


\section*{Single－strand mechanisms}


which
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\footnotetext{
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}


\[
\begin{equation*}
0^{2} \tag{正}
\end{equation*}
\]

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break \＆self－fold

separate
－Driven by specific and non－specific interactions
－The protofilaments are highly dynamic \＆flexible

Monomer addition

 ？
rest
－Driven
 


The protofitanens are highly dynamic \＆flexible

\[
e^{2}
\]
\(\square\)

\section*{Multi-strand protofilaments}

- short
- transient species - on-pathway
- more rigid than single protofilament precursors


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\section*{Multi-strand mechanisms}
- via spherical oligomers
- driven by non-specific interactions
- stabilized by specific interactions


- via breakage of single filaments
- rearrangements

- via tip merging of species
- long rearrangements

rearrange


\section*{Spherical oligomers \＆fibrils \\ iskunde en Informatica \\ oligomers \＆fibrils}


\(\qquad\)
\(\square\)都 正
                                正

\section*{Different type of coarse graining}

1
60-65
90-95
\begin{tabular}{|c|c|c|}
\hline N-terminus & NAC region & C-terminus \\
\hline \begin{tabular}{l}
- amphipathic (both hydrophilic and lipophilic) \\
- \(\alpha\)-helix, disordered
\end{tabular} & \begin{tabular}{l}
- hydrophobic \\
- building block for \(\alpha\)-synuclein aggregates \\
- \(\alpha\)-helix, \(\beta\)-sheets, disordered
\end{tabular} & \begin{tabular}{l}
- highly acidic \\
- negatively charged \\
- disordered
\end{tabular} \\
\hline
\end{tabular}


\section*{Question: Fibrillar growth}


**Woerdehoff et al. JMB 427:1428-1435 (2015)
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[^0]:    - Slightly curved structure

[^1]:    Wiskunde en Informatica

[^2]:    - 

